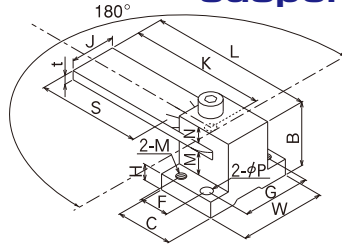


# Swing

A circular motion of functional parts attached on or suspended from the board

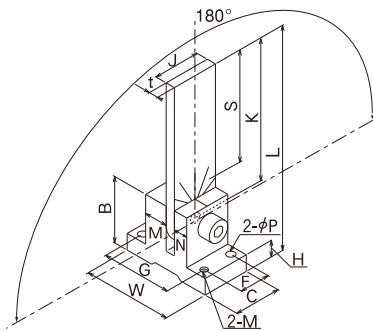


for mounting of Such as sensors and SW



1. In plane and circular movement against face
2. Scale with every 10°
3. Amplitude 180°

Part No.	J	S(valid)	K	t	M	N	B	C	H	W	L	F	G	2-φP	2-M	Cap screw	movable load N
MBX10-50	10	42	50	3	5	4	16.5	16	4.5	24	61	8	18	φ3.5	M3	M4	13
MBX10-75		67	75								86						11
MBX20-60	20	47	60	4	9.5	7.5	28.5	25	7.5	38	79	13	30	φ4.5	M4	M5	18
MBX20-90		77	90								109						15
MBX30-70	30	51	70	5	15	10	40.5	36	10.5	52	96	20	42	φ5.5	M5	M6	19
MBX30-100		81	100								126						18



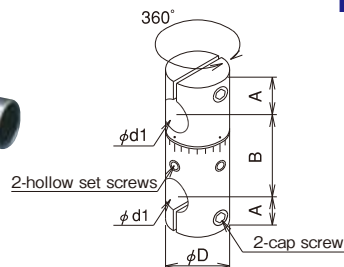
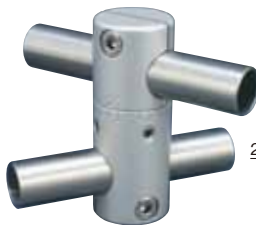
1. Vertical and circular movement against a face
2. Scale with every 10°
3. Amplitude 180°

※withholding load = edge position

Part No.	J	S(valid)	K	t	M	N	B	C	H	W	L	F	G	2-φP	2-M	Cap screw	Withstand load N
MBY10-50	10	37	50	3	8	5	22.5	20	6.5	32	66.5	13	25	φ3.5	M3	M4	49
MBY10-75		62	75								91.5						26
MBY20-60	20	46	60	4	10	6	28.5	20	7.5	38	80.5	13	30	φ3.5	M3	M5	109
MBY20-90		76	90								110.5						71
MBY30-70	30	51	70	5	15	10	40.5	30	10.5	52	100.5	16	42	φ5.5	M5	M6	192
MBY30-100		81	100								130.5						177

# Parallel two-shaft rotating type

for device positioning by variable pole clump



1. Scale with every 15°
2. Two-parallel shaft for 360° movement pivot
3. 2hollow-set screw sand fixing position

Part No.	φd1	φD	A	B	2-hollow set screws	2-cap screw
BC06-	φ 6	φ13	9	16.5	M3	M3
BC08-	φ 8	φ15	12	20.5		
BC09-	φ 9		12.5	21.5	M4	M4
BC10-	φ10	13	22.5			
BC12-	φ12	φ22	14	28	M5	M5
BC13-	φ13		29			
BC15-	φ15	φ25	17	33	M5	M5
BC16-	φ16		33.5			
BC19-	φ19.1	φ29	19	39	M5	M5
BC20-	φ20		20	40.5		